What is integrability of (discrete) variational systems?

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Based on:

1. Yu. S. Variational formulation of commuting Hamiltonian flows: multi-time Lagrangian 1-forms. J. Geom. Mechanics, 2013, **5**, No. 3, p. 365–379.

2. R. Boll, M. Petrera, Yu. S. *What is integrability of discrete variational systems?* Proc. Royal Soc. A, 2014, **470**, No. 2162, 20130550, 15 pp.

3. A. Bobenko, Yu. S. *Discrete pluriharmonic functions as solutions of linear pluri-Lagrangian systems*, Commun. Math. Phys. 2015, **336**, No. 1, p. 199–215.

4. Yu. S., M. Vermeeren. On the Lagrangian structure of *integrable hierarchies*, arXiv:1510.03724 [math-ph].

According to the spirit of Geometric Numerical Integration, use *variational integrators* to discretize Lagrangian systems.

But how should one take into account *integrability* of the original system?

And what does it mean for a Lagrangian system (continuous or discrete) to be integrable?

Recent development started with:

 S. Lobb, F.W. Nijhoff. Lagrangian multiforms and multidimensional consistency, J. Phys. A, 2009, 42, 4540103

who discovered closedness of Lagrangian 2-form on solutions of systems of quad-equations (for a part of ABS list).

- Theory of pluriharmonic functions: f : C^m → R minimizes the Dirichlet functional E_Γ = ∫_Γ |(f ∘ Γ)_z|²dz ∧ dz̄ along any holomorphic curve Γ : C → C^m.
- Baxter's Z-invariance of solvable models of statistical mechanics: invariance of the partition function under elementary local transformations of the underlying graph.
- Variational symmetries (classical work by E. Noether).

Pluri-Lagrangian problem, discrete time, d = 1

A *discrete 1-form* \mathcal{L} is a skew-symmetric function on directed edges of \mathbb{Z}^m , depending on a field $x : \mathbb{Z}^m \to \mathcal{X}$ (where \mathcal{X} is a vector space):

 $\mathcal{L}(n, n + e_i) = \Lambda_i(x, x_i) \quad \Leftrightarrow$

A discrete curve Γ in \mathbb{Z}^m is a concatenation of edges \mathfrak{e}_k .

Action functional along Γ :

$$S_{\Gamma} = \sum_{k \in \mathbb{Z}} \mathcal{L}(\mathfrak{e}_k).$$

$$\mathcal{L}(n, n-e_i) = -\Lambda_i(x_{-i}, x).$$



Problem. Find functions $x : \mathbb{Z}^m \to \mathcal{X}$ delivering critical points for the functional S_{Γ} along *any* discrete curve Γ in \mathbb{Z}^m .

2D corner equations

Theorem. Function $x : \mathbb{Z}^m \to \mathcal{X}$ solves the pluri-Lagrangian problem for $\mathcal{L}(n, n + e_i) = \Lambda_i(x, x_i)$, iff the following *2D corner equations* are satisfied:

$$\frac{\partial \Lambda_i(x_{-i}, x)}{\partial x} + \frac{\partial \Lambda_j(x, x_j)}{\partial x} = 0,$$

$$\frac{\partial \Lambda_i(x_{-i}, x)}{\partial x} - \frac{\partial \Lambda_j(x_{-j}, x)}{\partial x} = 0,$$

$$\frac{\partial \Lambda_i(x, x_i)}{\partial x} - \frac{\partial \Lambda_j(x, x_j)}{\partial x} = 0$$

(four equations per elementary square σ_{ij}).



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Definition. System of 2D corner equations is called *consistent*, if, for any square σ_{ij} , it has the minimal possible rank 2, i.e., if exactly two of these four equations are independent.

Remark. Standard (single-time) discrete EL equations are *consequences* of 2D corner equations:



If 2D corner equations are satisfied, then there exists $p : \mathbb{Z}^m \to T^* \mathcal{X}$ satisfying

$$p = rac{\partial \Lambda_i(x, x_i)}{\partial x} = -rac{\partial \Lambda_j(x_{-j}, x)}{\partial x}, \quad i, j = 1, \dots, m.$$

Theorem. 2D corner equations are consistent, iff symplectic maps $F_i : (x, p) \mapsto (x_i, p_i)$ defined by

$$p = rac{\partial \Lambda_i(x, x_i)}{\partial x}, \quad p_i = -rac{\partial \Lambda_i(x, x_i)}{\partial x_i},$$

commute, $F_i \circ F_j = F_j \circ F_i$.

Theorem. The following identities hold true on solutions of multi-time discrete Euler-Lagrange equations:

$$d\mathcal{L}(\sigma_{ij}) = \Lambda_i(x, x_i) + \Lambda_j(x_i, x_{ij}) - \Lambda_i(x_j, x_{ij}) - \Lambda_j(x, x_j) = \ell_{ij} = \text{const.}$$

Proof. Partial derivatives of the left-hand side with respect to each of x, x_i , x_j and x_{ij} vanish on solutions, according to the corner equations.

In particular, if all these constants ℓ_{ij} vanish, then the discrete 1-form \mathcal{L} is closed on solutions, so that the extremal value of the action functional S_{Γ} does not depend on the choice of the curve Γ connecting two given points in \mathbb{Z}^m .

Closedness of multi-time 1-form vs. spectrality

Let $F_{\lambda} : (x, p) \mapsto (\tilde{x}, \tilde{p})$ be a *1-parameter family* of commuting symplectic maps (*Bäcklund transformations*), with Lagrange function $\Lambda(x, \tilde{x}; \lambda)$.

For a second such map, we write $F_{\mu} : (x, p) \mapsto (\widehat{x}, \widehat{p})$.

From previous theorem:

$$\Lambda(\mathbf{x},\widetilde{\mathbf{x}};\lambda) + \Lambda(\widetilde{\mathbf{x}},\widehat{\widetilde{\mathbf{x}}};\mu) - \Lambda(\mathbf{x},\widehat{\mathbf{x}};\mu) - \Lambda(\widehat{\mathbf{x}},\widehat{\widetilde{\mathbf{x}}};\lambda) = \ell(\lambda,\mu).$$

Theorem. The discrete 1-form \mathcal{L} is closed on solutions of the multi-time Euler-Lagrange equations iff

 $\partial \Lambda(\mathbf{x}, \widetilde{\mathbf{x}}; \lambda) / \partial \lambda$

is a common integral of motion for all F_{μ} (*spectrality*; discovered on examples by Kuznetsov-Sklyanin (1998)).

Closedness of multi-time 1-form vs. spectrality (continued)

Proof. Due to skew-symmetry, $\ell(\lambda, \mu) = 0$ is equivalent to $\partial \ell(\lambda, \mu) / \partial \lambda = 0$, that is, to

$$\frac{\partial \Lambda(x,\widetilde{x};\lambda)}{\partial \lambda} - \frac{\partial \Lambda(\widehat{x},\widehat{\widetilde{x}};\lambda)}{\partial \lambda} = 0.$$

This is equivalent to saying that $\partial \Lambda(x, \tilde{x}; \lambda) / \partial \lambda$ is an integral of motion for F_{μ} .



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Example: discrete time Toda lattice

Lagrange function:

$$\Lambda(x,\widetilde{x};\lambda) = \frac{1}{\lambda} \sum_{k=1}^{N} \left(e^{\widetilde{x}_k - x_k} - 1 - (\widetilde{x}_k - x_k) \right) - \lambda \sum_{k=1}^{N} e^{x_{k+1} - \widetilde{x}_k}.$$

Lagrangian equations of motion:

$$\frac{1}{\lambda^2}\left(e^{\widetilde{x}_k-x_k}-e^{x_k-\widetilde{x}_k}\right)=e^{\widetilde{x}_{k+1}-x_k}-e^{x_k-\widetilde{x}_{k-1}}.$$

Symplectic map $(x, p) \mapsto (\tilde{x}, \tilde{p})$,

$$F_{\lambda}: \begin{cases} \boldsymbol{p}_{k} = \frac{1}{\lambda} \left(\boldsymbol{e}^{\widetilde{x}_{k}-x_{k}} - 1 \right) + \lambda \boldsymbol{e}^{x_{k}-\widetilde{x}_{k-1}}, \\ \widetilde{\boldsymbol{p}}_{k} = \frac{1}{\lambda} \left(\boldsymbol{e}^{\widetilde{x}_{k}-x_{k}} - 1 \right) + \lambda \boldsymbol{e}^{x_{k+1}-\widetilde{x}_{k}}. \end{cases}$$

Integrability of discrete time Toda lattice

 \mathcal{L} closed on solutions \Leftrightarrow generating function of integrals of motion:

$$P(x,p;\lambda) = \sum_{k=1}^{N} (\widetilde{x}_k - x_k),$$

where \tilde{x}_k should be expressed through p_k with the help of

$$e^{\widetilde{x}_k-x_k} = 1 + \lambda p_k - \lambda^2 e^{x_k-\widetilde{x}_{k-1}}.$$

One finds:

$$e^{P} = \operatorname{tr} U_{N}(x, p; \lambda) \cdots U_{2}(x, p; \lambda) U_{1}(x, p; \lambda),$$

where

$$U_k(x,p;\lambda) = \begin{pmatrix} 1+\lambda p_k & -\lambda^2 e^{x_k} \\ e^{-x_k} & 0 \end{pmatrix}.$$

A long-standing problem: integrability of variational systems. Solution: along the discretization path.

Equations are of elliptic type (à la Laplace equation).



Discrete hyperbolic systems: integrability = multidimensional consistency

3D consistency of quad-equations $Q(x, x_i, x_j, x_{ij}) = 0$:



- Discrete analog of commuting flows
- Zero curvature representation and Bäcklund transformations
- Equation can be imposed on arbitrary quad-graphs realized as quad-surfaces in Z^m

Difficulty: notions *evolution* and *commutativity* seem to be alien for elliptic systems. Difficult to come up with anything like 3D consistency for discrete elliptic (Laplace-type) systems.

Pluri-Lagrangian problem, discrete space-time, d = 2

Main idea: require solutions to be extremals not only on \mathbb{Z}^2 but on arbitrary quad-surfaces in \mathbb{Z}^m .

A *discrete 2-form* \mathcal{L} is a skew-symmetric function on oriented squares $\sigma_{ij} = (n, n + e_i, n + e_i + e_j, n + e_j)$ of \mathbb{Z}^m :

$$\mathcal{L}(\sigma_{ij}) = \Lambda_{ij}(\mathbf{x}, \mathbf{x}_i, \mathbf{x}_{ij}, \mathbf{x}_j) = -\mathcal{L}(\sigma_{ji}).$$

For a *discrete quad-surface* Σ in \mathbb{Z}^m , set: $S_{\Sigma} = \sum_{\sigma_{ij} \subset \Sigma} \mathcal{L}(\sigma_{ij})$.

Problem. Find functions $x : \mathbb{Z}^m \to \mathcal{X}$ delivering critical points for the action functional S_{Σ} for *any* quad-surface Σ in \mathbb{Z}^m .



3D corner equations

Theorem. For a given discrete 2-form $\mathcal{L}(\sigma_{ij}) = \Lambda_{ij}(x, x_i, x_{ij}, x_j)$, denote

$$\mathcal{S}^{ijk} = \mathcal{dL}(\sigma_{ijk}) = \Delta_k \mathcal{L}(\sigma_{ij}) + \Delta_i \mathcal{L}(\sigma_{jk}) + \Delta_j \mathcal{L}(\sigma_{ki})$$

Function $x : \mathbb{Z}^m \to \mathcal{X}$ solves the pluri-Lagrangian problem for \mathcal{L} , iff the following *3D corner equations* are satisfied:

$$\frac{\partial S^{ijk}}{\partial x} = 0, \quad \frac{\partial S^{ijk}}{\partial x_i} = 0, \quad \frac{\partial S^{ijk}}{\partial x_j} = 0, \quad \frac{\partial S^{ijk}}{\partial x_k} = 0,$$
$$\frac{\partial S^{ijk}}{\partial x_{ij}} = 0, \quad \frac{\partial S^{ijk}}{\partial x_{jk}} = 0, \quad \frac{\partial S^{ijk}}{\partial x_{ik}} = 0, \quad \frac{\partial S^{ijk}}{\partial x_{ijk}} = 0,$$

(eight equations per elementary cube σ_{ijk}). Symbolically: $\delta(d\mathcal{L}) = 0$, where δ stands for the "vertical" differential.

3D corners: elementary building blocks of quad-surfaces

Any vertex star in any quad-surface can be built from 3D corners (with extension into an extra dimension, if necessary).



3D corner equations: "elementary particles" for integrable Laplace type equations







Definition. System of corner equations is called *consistent*, if, for any cube σ_{ijk} , it has the minimal possible rank 2, i.e., if exactly two of these eight equations are independent.

Theorem. For any triple i, j, k, action S^{ijk} over an elementary cube is constant on solutions of corner equations:

$$d\mathcal{L}(\sigma_{ijk}) = S^{ijk}(x, \dots, x_{ijk}) = c^{ijk} = \text{const}$$

(mod
$$\partial S^{ijk}/\partial x = 0, \ldots, \partial S^{ijk}/\partial x_{ijk} = 0$$
).

Most interesting case: all $c^{ijk} = 0$, i.e., \mathcal{L} closed on solutions of corner equations.

Particular case: 3-point 2-form

For ABS equations:

 $\mathcal{L}(\sigma_{ij}) = \mathcal{L}(\mathbf{x}, \mathbf{x}_i, \mathbf{x}_j; \alpha_i, \alpha_j) = \mathcal{L}(\mathbf{x}, \mathbf{x}_i; \alpha_i) - \mathcal{L}(\mathbf{x}, \mathbf{x}_j; \alpha_j) - \Lambda(\mathbf{x}_i, \mathbf{x}_j; \alpha_i, \alpha_j).$

For such \mathcal{L} , action $d\mathcal{L}(\sigma_{ijk}) = S^{ijk}$ depends neither on x nor on x_{ijk} :



Corner equations for a 3-point 2-form

four-leg, five-point equations:

$$\psi(\mathbf{x}_i, \mathbf{x}_{ij}; \alpha_j) - \psi(\mathbf{x}_i, \mathbf{x}_{ik}; \alpha_k) - \phi(\mathbf{x}_i, \mathbf{x}_k; \alpha_i, \alpha_k) + \phi(\mathbf{x}_i, \mathbf{x}_j; \alpha_i, \alpha_j) = \mathbf{0},$$

$$\psi(\mathbf{x}_{ij}, \mathbf{x}_i; \alpha_j) - \psi(\mathbf{x}_{ij}, \mathbf{x}_j; \alpha_i) - \phi(\mathbf{x}_{ij}, \mathbf{x}_{ik}; \alpha_j, \alpha_k) + \phi(\mathbf{x}_{ij}, \mathbf{x}_{jk}; \alpha_i, \alpha_k) = \mathbf{0}.$$



Here, we introduced the notation

$$\psi(\mathbf{x},\mathbf{y};\alpha) = \frac{\partial L(\mathbf{x},\mathbf{y};\alpha)}{\partial \mathbf{x}}, \quad \phi(\mathbf{x},\mathbf{y};\alpha,\beta) = \frac{\partial \Lambda(\mathbf{x},\mathbf{y};\alpha,\beta)}{\partial \mathbf{x}}.$$

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From corner equations to planar Laplace type equations



Theorem. For the discrete 2-forms \mathcal{L} for quad-equations of the ABS list, the corresponding systems of 3D corner equations are consistent, as well. Moreover, the 2-form \mathcal{L} is closed on solutions of 3D corner equations.

Relation between closedness of \mathcal{L} and integrability:

Theorem. System of 3D corner equations for \mathcal{L} admits parameter-dependent families of *conservation laws*: $\Delta_j F_{ik} = \Delta_k F_{ij}$, where

$$F_{ij} = \frac{\partial L(x, x_i, \alpha_i)}{\partial \alpha_i} - \frac{\partial \Lambda(x_i, x_j, \alpha_i - \alpha_j)}{\partial \alpha_i}$$

(d = 2 analog of spectrality).

Proof: Differentiate $S^{ijk} = 0$ w.r.t. α_i .

We propose the notion of pluri-Lagrangian systems as integrability of discrete (and continuous) variational systems.

- ► (Almost) closedness of the Lagrangian form (*dL* = const) on solutions of the pluri-Lagrangian system built-in.
- ► Closedness of the Lagrangian form (*dL* = 0) on solutions is related to existence of integrals of motion for *d* = 1 (resp. conservation laws for *d* = 2).
- Classification of pluri-Lagrangian systems looks promising.